



What's in a Plan?

And how did it get there, anyway?

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Plan Contents: Structure Definition

```
typedef struct Plan
{
    NodeTag          type;

    /* estimated execution costs for plan (see costsize.c for more info) */
    Cost             startup_cost; /* cost expended before fetching any tuples */
    Cost             total_cost;   /* total cost (assuming all tuples fetched) */

    /* planner's estimate of result size of this plan step */
    double           plan_rows;    /* number of rows plan is expected to emit */
    int              plan_width;   /* average row width in bytes */

    /*
     * information needed for parallel query
     */
    bool             parallel_aware; /* engage parallel-aware logic? */
    bool             parallel_safe; /* OK to use as part of parallel plan? */

    /*
     * Common structural data for all Plan types.
     */
    int              plan_node_id; /* unique across entire final plan tree */
    List             *targetlist;  /* target list to be computed at this node */
    List             *qual;        /* implicitly-ANDed qual conditions */
    struct Plan      *lefttree;    /* input plan tree(s) */
    struct Plan      *righttree;
    List             *initPlan;    /* Init Plan nodes (un-correlated expr
                                   * subselects) */

    /*
     * Information for management of parameter-change-driven rescanning
     */
    Bitmapset       *extParam;
    Bitmapset       *allParam;
} Plan;
```

Plan Contents: By Category

- Node Tag
- Costing Information
- Parallel Query Support
- Target List & Qual
- Left & Right Subtrees
- InitPlans
- extParam & allParam
- Type-specific information

Costing Information

- PostgreSQL first generates paths representing possible query plans; winning paths are converted to plans.
- Costs are important at the path stage because they let us determine which paths are best, but we save the information in the final plan.

```
/*
 * estimated execution costs for plan
 */
Cost                startup_cost;
Cost                total_cost;

/*
 * planner's estimate of result size
 */
double              plan_rows;
int                 plan_width;    /* in bytes/row */
```

Costing Information: Uses

- EXPLAIN.
- For a hash join or hashed subplan, row count and width are used to set the initial size of the hash table.
- For a hash join, should we fetch the first outer tuple before or after building the hash table?
- Decide between AlternativeSubPlans.
- Decide between custom plans and generic plans.

Parallel Query

```
/* engage parallel-aware logic? */  
bool                parallel_aware;  
  
/* OK to use as part of parallel plan? */  
bool                parallel_safe;  
  
/* unique across entire final plan tree */  
int                 plan_node_id;
```

Parallel Query: Motivation

- Why do we need the `parallel_aware` flag?

Gather

-> Merge Join

-> Parallel Index Scan on a

-> Index Scan on b

- Why do we need the `plan_node_id`?

Gather

-> Append

-> Parallel Seq Scan on p1

-> Parallel Seq Scan on p2

-> Parallel Seq Scan on p3

Target List, Filter, Left & Right Subtrees (1)

```
/* target list to be computed at this node */  
List      *targetlist;  
  
/* implicitly-ANDed qual conditions */  
List      *qual;  
  
/* input plan tree(s) */  
struct Plan *lefttree;  
struct Plan *righttree;
```

Target List, Filter, Left & Right Subtrees (2)

Merge Left Join

Output: a.q2, b.q1

Merge Cond: (a.q2 = (COALESCE(b.q1, '1'::bigint)))

Filter: (COALESCE(b.q1, '1'::bigint) > 0)

-> Sort

Output: a.q2

Sort Key: a.q2

-> Seq Scan on public.int8_tbl a

Output: a.q2

-> Sort

Output: b.q1, (COALESCE(b.q1, '1'::bigint))

Sort Key: (COALESCE(b.q1, '1'::bigint))

-> Seq Scan on public.int8_tbl b

Output: b.q1, COALESCE(b.q1, '1'::bigint)

Left, Right, Center Right, Center Left?

Append

- > Seq Scan on foo
- > Seq Scan on bar
- > Seq Scan on baz
- > Seq Scan on quux

InitPlans & SubPlans

```
regression=# explain (costs off, verbose) select f1,  
(select odd from tenk1 where unique1 = f1) from int4_tbl  
where f1 = (select min(abs(f1)) from int4_tbl);
```

```
Seq Scan on public.int4_tbl
```

```
Output: int4_tbl.f1, (SubPlan 1)
```

```
Filter: (int4_tbl.f1 = $1)
```

```
InitPlan 2 (returns $1)
```

```
-> Aggregate
```

```
Output: min(abs(int4_tbl_1.f1))
```

```
-> Seq Scan on public.int4_tbl int4_tbl_1
```

```
Output: int4_tbl_1.f1
```

```
SubPlan 1
```

```
-> Index Scan using tenk1_unique1 on public.tenk1
```

```
Output: tenk1.odd
```

```
Index Cond: (tenk1.unique1 = int4_tbl.f1)
```

InitPlans, not SubPlans!

- Each Plan node carries a list of associated initPlans.
- SubPlans are not listed; they just appear in expressions. The executor builds a per-node list at runtime.

```
List *initPlan; /* Init Plan nodes (un-correlated  
                * expr subselects) */
```

extParam & allParam

```
/*
 * Information for parameter-change-driven rescanning
 *
 * extParam includes the paramIDs of all external
 * PARAM_EXEC params affecting this plan node or its
 * children. setParam params from the node's
 * initPlans are not included, but their extParams
 * are.
 *
 * allParam includes all the extParam paramIDs, plus
 * the IDs of local params that affect the node (i.e.,
 * the setParams of its initplans). These are all
 * the PARAM_EXEC params that affect this node.
 */
Bitmapset *extParam;
Bitmapset *allParam;
```

extParam & allParam: Example

```
explain (verbose, costs off)
select 1 = all (select (select 1));
```

Result

```
Output: (SubPlan 2)
```

```
SubPlan 2
```

```
-> Materialize ← extParam empty, allParam = {$0}
```

```
Output: ($0)
```

```
InitPlan 1 (returns $0)
```

```
-> Result
```

```
Output: 1
```

```
-> Result
```

```
Output: $0
```

extParams & allParams: Execution

- allParam is used to decide which nodes to reset when we need to rescan.
- For example, we can rescan a sort either by rereading the existing output or by throwing away the old output, regenerating the input, and sorting again.
- If the sort's input depends on a parameter which has changed, we need to do the latter; otherwise it's faster to do the former.
- extParam is also used for this purpose ... barely. It's mostly used when assembling the final plan, rather than at execution time.

Where's the Parameter?

Nested Loop

-> Seq Scan on int4_tbl

-> Append

-> Index Scan using t3i on t3 a

Index Cond: (expensivefunc(x) = int4_tbl.f1)

-> Index Scan using t3i on t3 b

Index Cond: (expensivefunc(x) = int4_tbl.f1)

Where's the Parameter?

Nested Loop

-> Seq Scan on int4_tbl

-> Append ← *extParam = allParam = {\$0}*

-> Index Scan using t3i on t3 a ← *here too*

Index Cond: (expensivefunc(x) = int4_tbl.f1)

-> Index Scan using t3i on t3 b ← *and also here*

Index Cond: (expensivefunc(x) = int4_tbl.f1)

EXPLAIN vs. Reality – So Far

- `parallel_safe` flag is not displayed.
- `plan_node_id` is not displayed.
- `InitPlans` and `SubPlans` are displayed in the same way, but only `InitPlans` are really attached that way.
- `extParam` and `allParam` are not displayed, although you can infer something about them from the `InitPlan` display (and from knowledge of how Nested Loops work).

Expression Deparsing: It's all a lie!

Nested Loop Left Join

Output: `"*VALUES*".column1, i1.f1, (666)`

Join Filter: `("*VALUES*".column1 = i1.f1)`

-> Values Scan on `"*VALUES*"`

Output: `"*VALUES*".column1`

-> Materialize

Output: `i1.f1, (666)`

-> Nested Loop Left Join

Output: `i1.f1, 666`

-> Seq Scan on `public.int4_tbl i1`

Output: `i1.f1`

-> Index Only Scan using `tenk1_unique2` on
`public.tenk1 i2`

Output: `i2.unique2`

Index Cond: `(i2.unique2 = i1.f1)`

Expression Deparsing: The lie exposed!

Nested Loop Left Join

Output: OUTER.1, INNER.1, INNER.2

Join Filter: (OUTER.1 = INNER.1)

-> Values Scan on "*VALUES*"

Output: "*VALUES*".column1

-> Materialize

Output: OUTER.1, OUTER.2

-> Nested Loop Left Join

Output: OUTER.1, 666

-> Seq Scan on public.int4_tbl i1

Output: i1.f1

-> Index Only Scan using tenk1_unique2 on
public.tenk1 i2

Output: i2.unique2

Index Cond: (i2.unique2 = \$0)

Expression Deparsing: Explained

- When we initially generated paths, references to table columns (internally called “Var” nodes) and expressions in target list and expressions refer to the table that will really provide the value.
- But at execution time, it’s not useful to know the original source of the value – we need to know from where we can obtain it.
- One of the last stages of planning is to replace Vars and expressions with Vars that refer to the “outer” or “inner” plan.

Thanks

- Any Questions?